

Stochastic Modeling with Randomized Markov Bridges and Conditioned Stochastic Differential Equations

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State Variable Y

- Commodities: Spot price: $(f(Y_t))_{t \geq 0}$, Forward price (martingale): $\mathbb{E}[f(Y_T) | \mathcal{F}_t]$,
- Dividend paying asset: $\sum_{i=j}^N \mathbb{E} \left[e^{-\rho(T_i-t)} \delta_i(Y_{T_i}) \mid \mathcal{F}_t \right]$ ($T_i \geq t$ for $i = j, \dots, N$),
- Interest-rate related, $(r(Y_t))_{t \geq 0}$: short rate, $\mathbb{E} \left[e^{-\int_t^T r(Y_u) du} g(Y_T) \mid \mathcal{F}_t \right]$.

When Y is **Markov**, it generates the market information (**filtration**),

$$\begin{aligned} \mathbb{E}[f(Y_T) | \mathcal{F}_t] &= \mathbb{E}[f(Y_T) | \mathcal{F}_t^Y] \\ &= \mathbb{E}[f(Y_T) | Y_t] = \left\{ \int_{\mathbb{R}^n} f(y) P(t, x, T, dy) \right\} \Big|_{x=Y_t}, \end{aligned}$$

$$P(t, x, u, dy) := \mathbb{P}(Y_u \in dy | Y_t = x), \quad t < u,$$

$$\mathcal{F}_t^Y := \sigma(Y_s, 0 \leq s \leq t).$$

Problem

Want to modify Y in such a way as to satisfy

$$\mathbb{Y} := (Y_{T_1}, \dots, Y_{T_N}) \sim G(dy),$$

- $0 = T_0 < T_1 < \dots < T_N = T$, fixed constant times,
- $G(dy)$: given law on $E^N = (\subset \mathbb{R}^N)$, state space of \mathbb{Y} .

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Requirements:

- “Minimal” modification in a certain sense,
- It may be better to reserve
 - ◆ Markovian property, Martingale property, ...

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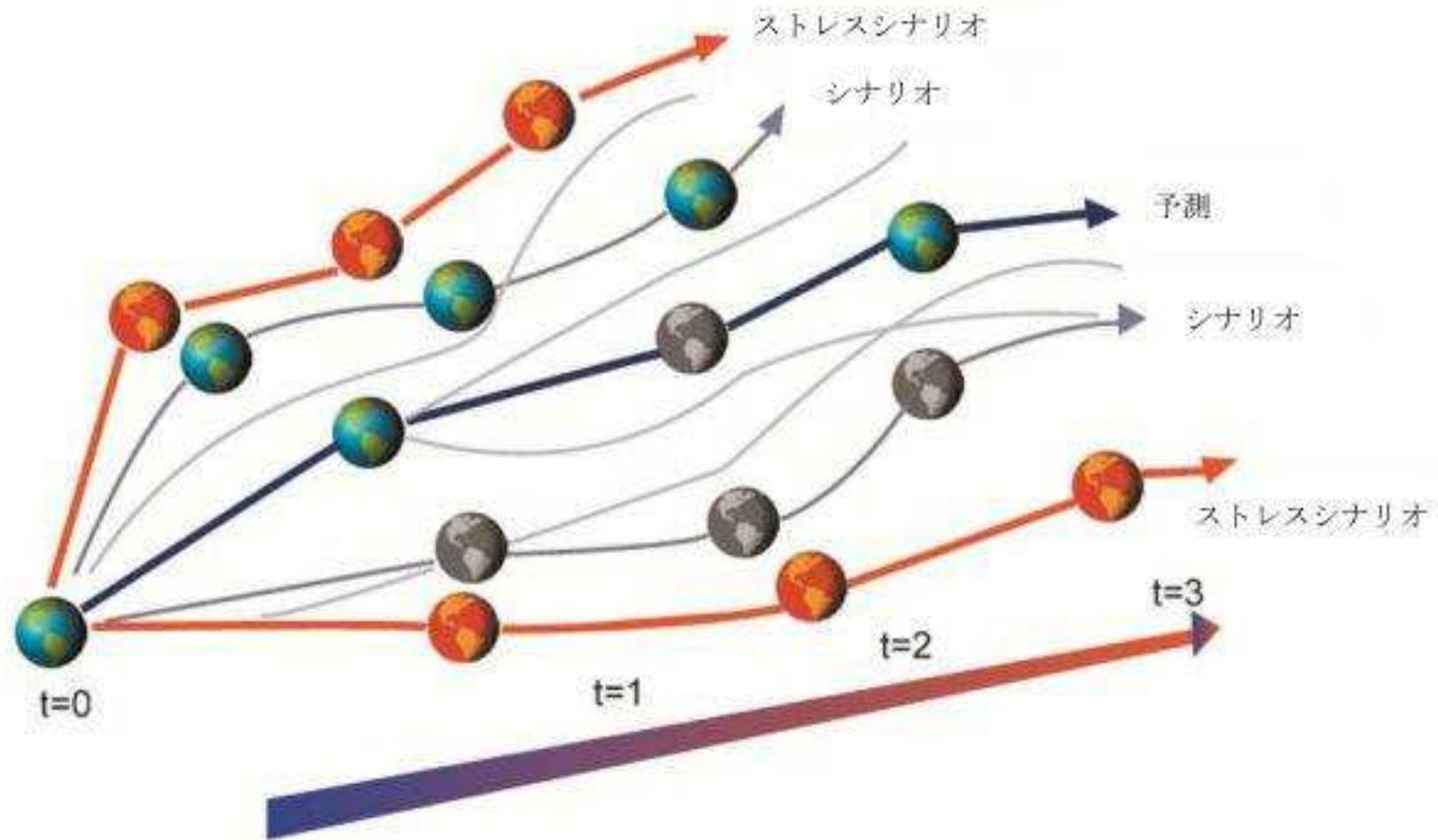
Approaches:

- Madan and Yor (2003): Three constructions of Markovian martingale,
 - Obloj and Spoida (2013): Iterated Azéma-Yor embedding,
 - Fan, Hamza and Klebaner (2015): Two constructions for self-similar Markovian martingales
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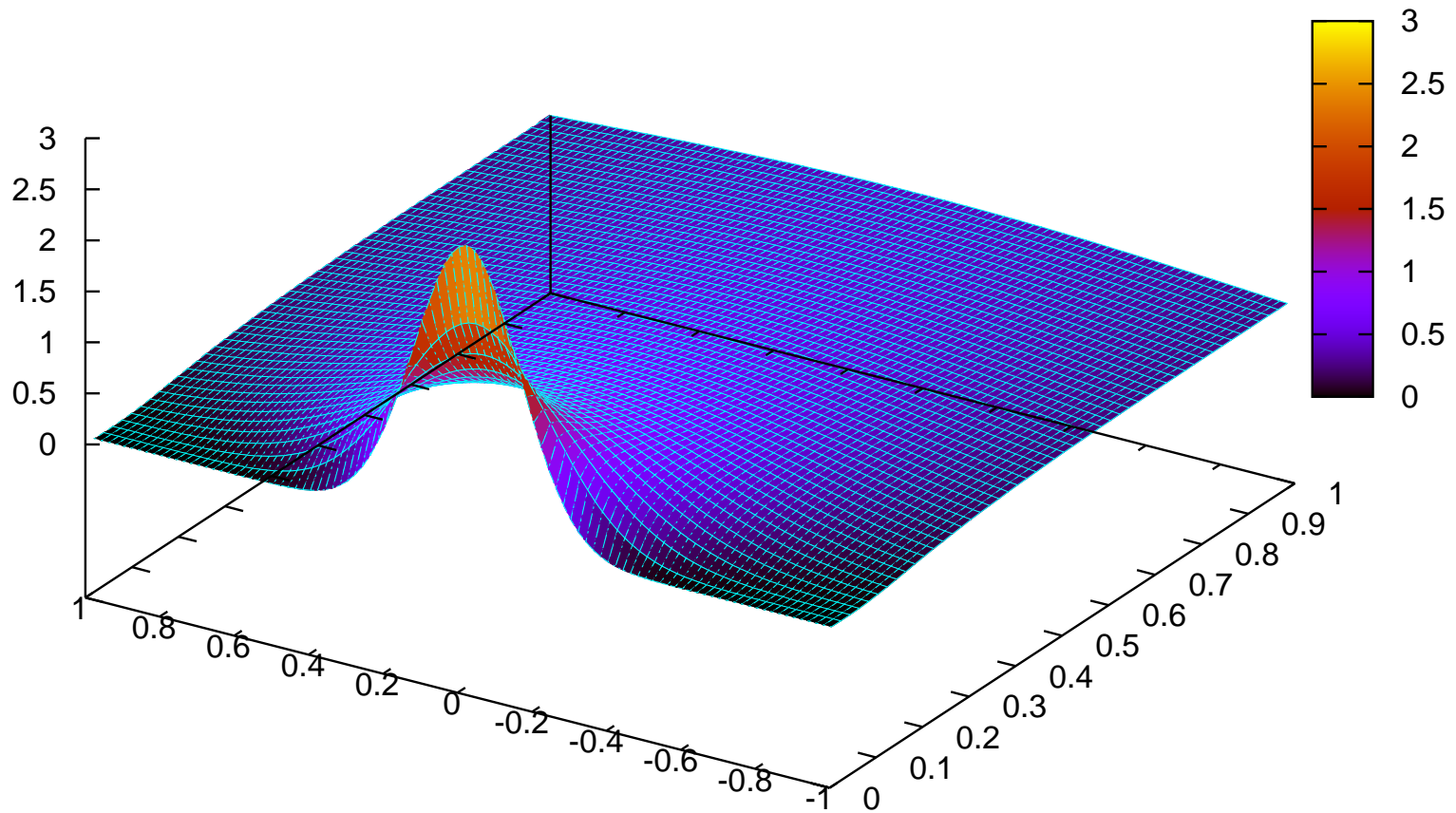
Motivations (for financial studies)

- Flexible modeling of cashflows,
- Fitting implied volatility curves (for option pricing models),
 - ◆ Breeden-Litzenberger (1978): can recover the marginal pdf of the law of the underlying asset.
- Stochastic stress test model,
 - ◆ Hand-pick (deterministic) scenarios ???
 - ◆ Randomized (i.e., the law of) stress scenarios: Breuer and Csiszar (2013)
↔ Entropic VaR (Föllmer and Knispel, 2011),
 - ◆ Insurance: long-term, multi-period (e.g., several years) stress testing,
 - Want to “stochastically interpolate” the randomized scenarios from a dynamic valuation point of view.

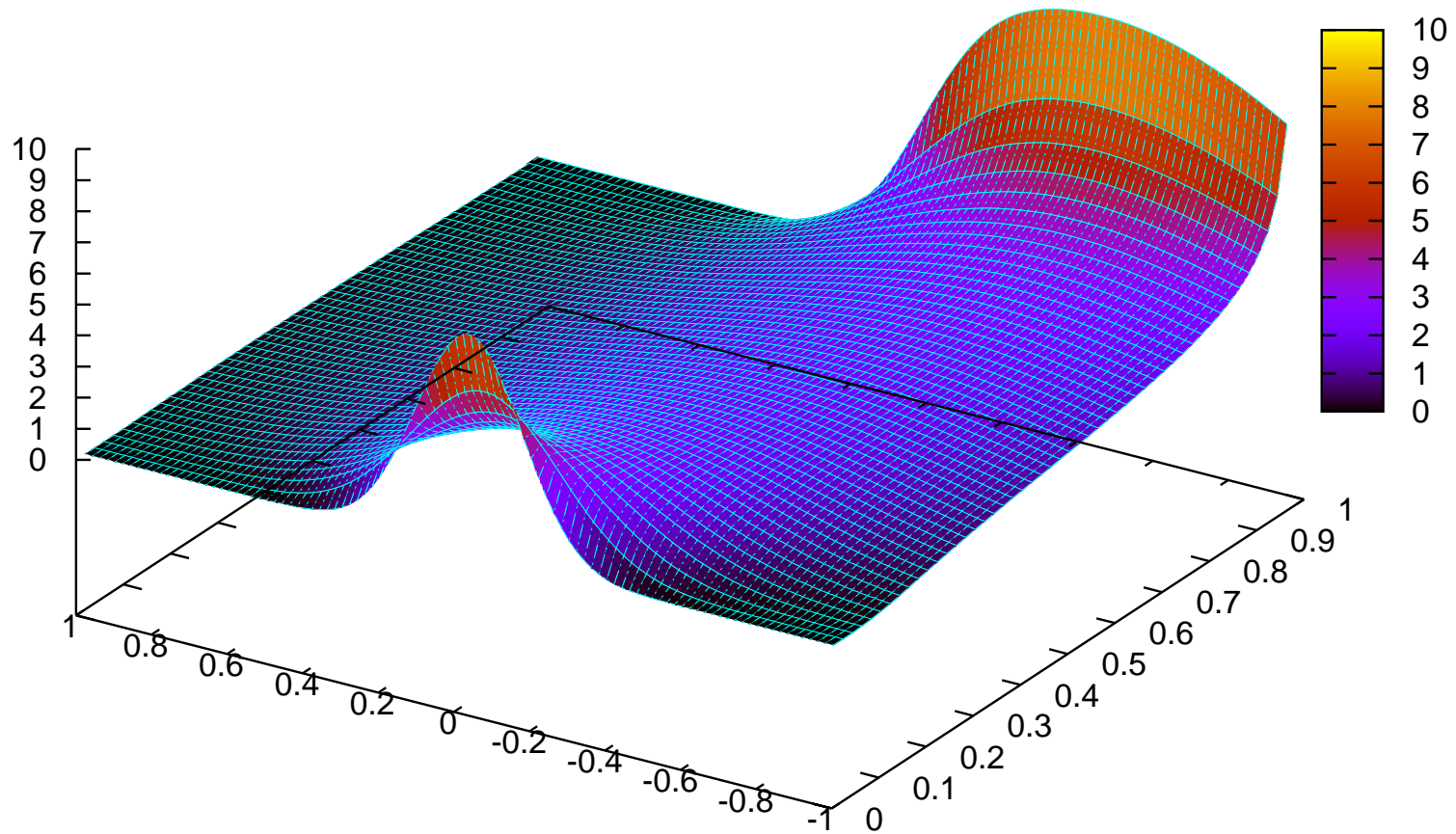
IAA: Stress Testing and Scenario Analysis (2013)



Marginal Densities of BM



Marginal Densities of CSDE: $X_1 \sim \text{Exp}(1)$



Plan

- “Strong” approach: RMB and filtering.
 - ◆ Ref. Brody, Hughston and Macrina (2008): RBB, Hoyle, Hughston and Macrina (2011): RLB, Filipovic, Hughston and Macrina (2012): attempt to get a local-vol, ..., Macrina and S (2017).
- “Weak” approach: CSDE (Baudoin, 2002).
- Single marginal to multiple marginals
- Skewed class (skew-normal diffusions)

“Strong” Approach ($N = 1$ Case for simplicity)

Setup:

- $(Y_t^{(y)})_{t \in [0, T]}$: (time-homogeneous) Markov process, $Y_0^{(y)} = y$. Let

$$\tilde{P}_t(x, dy) := \tilde{p}_t(x, y) dy := \mathbb{P}(Y_t \in dy | Y_0 = x).$$

- $(Y_t^{(y, T, z)})_{t \in [0, T]}$: Markov bridge, $Y_0^{(y, T, z)} = y$, $Y_T^{(y, T, z)} = z$ a.s.
- X : r.v., $\sim G$, indep. of Y , (system).
- $Z_t := Y_t^{(y, T, X)}$, $t \in [0, T]$, (noisy observation).
- $\mathcal{F}_t^Z := \sigma(Z_u; u \in [0, t]) \vee \mathcal{N}$, $t \in [0, T]$.

Targets:

- Filtering: $\pi_t(dx) := \mathbb{P}(X \in dx | \mathcal{F}_t^Z)$.
- Dynamics of $\mathbb{E}[f(X) | \mathcal{F}_t^Z] = \mathbb{E}[f(Z_T) | \mathcal{F}_t^Z]$.
- Dynamics of Z wrt $(\mathcal{F}_t^Z)_{t \in [0, T]}$.
- “Transition probability”: $q_{s, t}(dx) := \mathbb{P}(Z_t \in dx | \mathcal{F}_s^Z)$ ($s \leq t$).

Constructing MB (Fitzsimmons et al, 1993)

- On the canonical path-space Ω_T^1 endowed with the natural filtration $(\mathcal{F}_t^1)_{t \in [0, T]}$, denote the law of $Y^{(y)}$ by $\tilde{\mathbb{P}}_y^1$.
- Assume the duality, i.e., $\exists (\hat{Y}, (\hat{P}_t)_{t \geq 0})$, so that

$$\int_E (\tilde{P}_t f_1)(x) f_2(x) m(dx) = \int_E f_1(x) (\hat{P}_t f_2)(x) m(dx),$$

$$(\tilde{P}_t f_1)(x) := \int_E f_1(y) \tilde{P}_t(x, dy), \quad (\hat{P}_t f_2)(x) := \int_E f_2(y) \hat{P}_t(x, dy).$$

- The law of MB $(Y_t^{(y, T, z)})_{t \in [0, T]}$ on $(\Omega_T^1, \mathcal{F}_{T-}^1)$ is $\mathbb{P}_{y, z}^1$, where

$$d\mathbb{P}_{y, z}^1 \Big|_{\mathcal{F}_t^1} := \frac{\tilde{p}_{T-t}(Y_t, z)}{\tilde{p}_T(y, z)} d\tilde{\mathbb{P}}_y^1 \Big|_{\mathcal{F}_t^1},$$

- On $(\Omega, \mathcal{F}_{T-}, \mathbb{P}_{y, z}^1)$ the Markov bridge process that satisfies $\mathbb{P}_{y, z}^1(Y_0 = y, Y_{T-} = z) = 1$ is determined.
- $\mathbb{P}_{y, z}^1$ is a (regular) version of $\tilde{\mathbb{P}}_y^1(\cdot | Y_{T-} = z)$ and $T-$ can be change to T .

Constructing RMB

- Define X on another probability space $(\Omega^2, \mathcal{F}^2, \mathbb{P}^2)$. Recall $G = \mathbb{P}^2 \circ X^{-1}$.
- On $(\Omega, \mathcal{F}_T, \mathbb{P}_y) := (\Omega^1 \times \Omega^2, \mathcal{F}_T^1 \otimes \mathcal{F}^2, \tilde{\mathbb{P}}_y^1 \otimes \mathbb{P}^2)$, we (want to) construct

$$Z_t(\omega_1, \omega_2) := Y_t^{(y, T, X(\omega_2))}(\omega_1), \quad t \in [0, T].$$

- Starting with $(Y_t^{(y)})_{t \in [0, T]}$ the solution to a Markovian SDE, we can construct the associated MB $(Y_t^{(y, T, z)})_{t \in [0, T]}$ as the solution to an SDE. Then, we can discuss the regularity (measurability) $z \mapsto Y^{(y, T, z)}$.
- Chaumont and Uribe Bravo (2011): weak continuity of $\mathbb{P}_{y, z}^1$ wrt z .

Filtering Results (1)

- $\mathbb{P}(X \in dz | \mathcal{F}_t^Z) = \pi_t(dz | Z_t, Z_0) = \frac{\frac{\tilde{p}_{T-t}(Z_t, z)}{\tilde{p}_T(Z_0, z)} G(dz)}{\int_E \frac{\tilde{p}_{T-t}(Z_t, z')}{\tilde{p}_T(Z_0, z')} G(dz')} \quad (0 \leq t < T).$
- $\mathbb{P}(Z_t \in dz | \mathcal{F}_s^Z) = q_{s,t}(dz | Z_s, Z_0) = q(s, Z_s; t, z | Z_0) dz \quad (0 \leq s < t < T),$ where

$$q(s, x; t, y | z_0) := \frac{\tilde{p}_{t-s}(x, y) \left\{ \int_E \frac{\tilde{p}_{T-t}(y, z)}{\tilde{p}_T(z_0, z)} G(dz) \right\}}{\int_E \frac{\tilde{p}_{T-s}(x, z')}{\tilde{p}_T(z_0, z')} G(dz')}.$$

For a **fixed** z_0 , the Chapman-Kolmogorov identity holds:

$$q(s, x; u, z | z_0) = \int_E q(s, x; t, y | z_0) q(t, y; u, z | z_0) dy$$

for $0 < s < t < u < T$ and $x, y, z \in E$.

Filtering Results (2): Kushner-Stratonovich equation

Consider $dY_t = b(Y_t)dt + \sigma(Y_t)dW_t$. For

$$S_t := \pi_t(f) := \int_E f(y)\pi_t(dy) = \mathbb{E} [f(X) | \mathcal{F}_t^Z],$$

we obtain

$$\pi_t(f) = \pi_0(f) + \int_0^t \{ \pi_s (f \nabla \ell_s) - \pi_s(f) \pi_s (\nabla \ell_s) \}^\top (\sigma \sigma^\top)^{1/2}(Z_s) dU_s,$$

where

- $\ell_s(z) := \ln \tilde{p}_{T-s}(Z_s, z),$
- $U_t := \int_0^t (\sigma \sigma^\top)^{-1/2}(Z_s) \left[dZ_s - \left\{ b(Z_s) + (\sigma \sigma^\top)(Z_s) \pi_s(\nabla \ell_s) \right\} ds \right],$
 \mathcal{F}_t^Z -Brownian motion (“innovation” process)
- SDE for (Z, \mathcal{F}_t^Z) can be written down, too.

Filtering Results (2): Kushner-Stratonovich equation

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 \mathcal{F}_t^Z -Brownian motion (“innovation” process)
- SDE for (Z, \mathcal{F}_t^Z) can be written down, too.
- SV model s.t. $f^{-1}(S_T) \sim G.$

“Weak” Approach (Baudoin, 2002)

- Y : sol. of (Markovian) SDE on the canonical space $C([0, T], E)$, ($E \subset \mathbb{R}^n$).
- $\mathbb{Y} := (Y_{T_1}, \dots, Y_{T_N})$: E^N -valued r.v. (or some segment of the trajectory Y).
- G : law on \mathbb{R}^N .
- **Minimal probability:**

$$\mathbb{P}_{y_0}^G(A) := \int_E \mathbb{P}(A | \mathbb{Y} = y, Y_0 = y_0) G(dy), \quad A \in \mathcal{F}_T,$$

which satisfies i) $\mathbb{E}^G[H | \mathbb{Y}] = E[H | \mathbb{Y}]$ for $\forall H$, ii) $\mathbb{Y} \sim G$ under \mathbb{P}^G .
If $G(dy) = g(y)dy$, then,

$$d\mathbb{P}_{y_0}^G = \left(\frac{g}{f} \right) (\mathbb{Y} | y_0) d\mathbb{P}_{y_0},$$

$$f(y | y_0) dy := \mathbb{P}(\mathbb{Y} \in dy | Y_0 = y_0) = \prod_{j=1}^N \tilde{p}_{T_j - T_{j-1}}(y_{j-1}, y_j) dy.$$

Suppose $N = 1$, for example.

- For $t \in [0, T)$,

$$\frac{d\mathbb{P}_{y_0}^G}{d\mathbb{P}} \Big|_{\mathcal{F}_t} = \mathbb{E} \left[\frac{g(X_T)}{\tilde{p}_T(y_0, Y_T)} \Big| \mathcal{F}_t \right] = \int_E \frac{\tilde{p}_{T-t}(Y_t, y)}{\tilde{p}_T(y_0, y)} G(dy).$$

- $(\mathbb{P}^G, \mathcal{F}_t)$ -dynamics of Y :

$$dY_t = \left\{ b(Y_t) + (\sigma\sigma^\top)(Y_t) \nabla \Lambda(t, Y_t | Y_0) \right\} dt + \sigma(Y_t) dW_t^G, \quad t \in [0, T),$$

$$\Lambda(t, y | y_0) := \log \left\{ \int_E \frac{\tilde{p}_{T-t}(y, z)}{\tilde{p}_T(y_0, z)} G(dz) \right\}.$$

- Transition/conditional probability formulas same as those of “strong” approach.

“Minimality” of \mathbb{P}^G

$$\min_{\mathbb{Q} \in \mathcal{P}_{G,h}} \mathbb{E} \left[h \left(\frac{d\mathbb{Q}}{d\mathbb{P}} \right) \right] = \mathbb{E} \left[h \left(\frac{d\mathbb{P}^G}{d\mathbb{P}} \right) \right],$$

where $h : [0, \infty) \rightarrow \mathbb{R}$: convex and set

$$\mathcal{P}_{G,h} := \left\{ \mathbb{Q} \mid \begin{array}{l} \text{prob. measure on } (\Omega, \mathcal{F}_T), \mathbb{Q} \ll \mathbb{P}, \\ Y \sim G \text{ under } \mathbb{Q}, \mathbb{E} \left| h \left(\frac{d\mathbb{Q}}{d\mathbb{P}} \right) \right| < \infty \end{array} \right\},$$

assuming $\int_E \left| h \left(\frac{dG}{d\mathbb{P}_Y} \right) \right| d\mathbb{P}_Y < \infty$, $\mathbb{P}_Y(dy) := \mathbb{P}(Y \in dy)$.

- $h(x) = x \log x$: relative entropy,
- $h(x) = x^2 - 1$: variance,

Skew-Normal Diffusion (1)

Let

$$dY_t = (k + KY_t)dt + \Sigma dW_t, \quad Y_0 \in \mathbb{R}^n,$$

$k \in \mathbb{R}^n$, $K, \Sigma \in \mathbb{R}^{n \times n}$ s.t. $\Sigma \Sigma^\top > 0$, and W : BM. Then,

$$\mathbb{P}(Y_t \in dz | Y_s = y) = \tilde{p}_{t-s}(y, z) dz = \phi_n(z - \mu_t(y), V_t) \quad 0 \leq s < t,$$

where

$$\phi_n(z; V_t) := \frac{1}{(2\pi)^{\frac{n}{2}} \sqrt{\det(V_t)}} \exp\left(-\frac{1}{2} z^\top V_t^{-1} z\right),$$

$$\mu_t(y) := e^{tK} y + \left(\int_0^t e^{sK} ds\right) k,$$

$$V_t := \int_0^t e^{sK} \Sigma \Sigma^\top e^{sK^\top} ds.$$

Skew-Normal Diffusion (2)

First, consider $N = 1$ case. Choose

$$G(dy) := f_{\text{GMSN}}(y; a, b, A, B, C) dy,$$

$$f_{\text{GMSN}}(x; a, b, A, B, C) := \frac{1}{\Phi_m(Cb - a, A + CBC^\top)} \phi_n(x - b, B) \Phi_m(Cx - a, A),$$

$a \in \mathbb{R}^m$, $b \in \mathbb{R}^n$, $A \in \mathbb{S}_{++}^m$, $B \in \mathbb{S}_{++}^n$, $C \in \mathbb{R}^{m \times n}$, $m \in \mathbb{N}$, $n \in \mathbb{N}$, and

$$\Phi_m(x; A) := \int_{\prod_{i=1}^m (-\infty, x_i]} \phi_m(y; A) dy,$$

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$$\Phi_m(x; A) := \int_{\prod_{i=1}^m (-\infty, x_i]} \phi_m(y; A) dy,$$

Introduced by Gupta et al. (2004). Actually,

$$\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} a \\ b \end{pmatrix}, \begin{pmatrix} A + CBC^\top & -CB \\ -BC^\top & B \end{pmatrix} \right),$$

then, $X_2 | \{X_1 \leq Cb\} \sim \text{GMSN}(a, b, A, B, C)$.

Skew-Normal Distribution

Many sub(super)-classes of GMSN are studied by (mainly) statisticians.

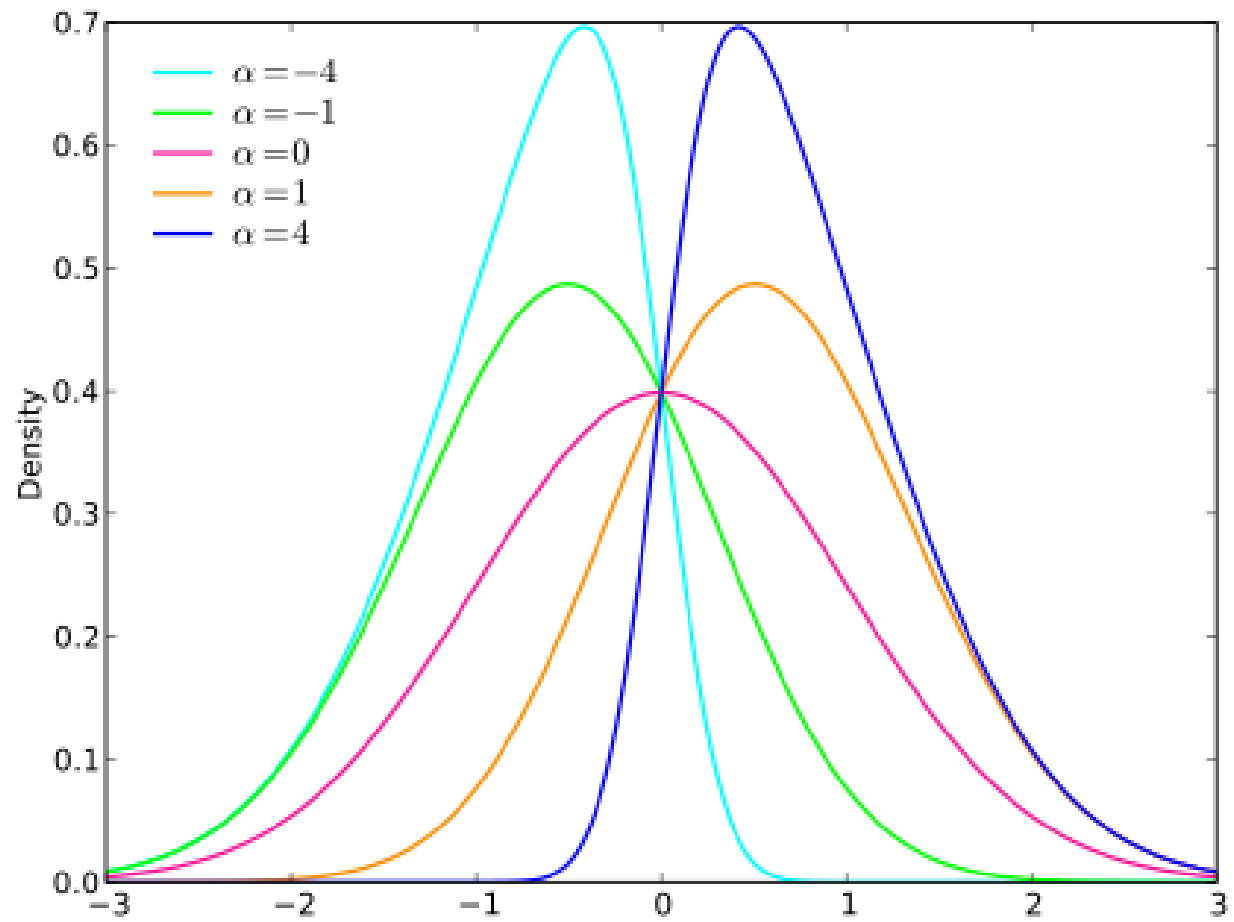
- Can refer to Monograph by Azzalini and Capitanio (2013).
- \exists Several ways of constructions.
- The univariate SN density: letting $m = n = 1$, and

$$\begin{aligned} f_{\text{USN}}(x; \mu, \sigma, \alpha) &:= f_{\text{GMSN}}\left(x; \frac{\alpha\mu}{\sigma}, \mu, 1, \sigma, \frac{\alpha}{\sigma}\right) \\ &= \frac{2}{\sigma} \phi_1\left(\frac{y - \mu}{\sigma}; 1\right) \Phi_1\left(\alpha \left(\frac{y - \mu}{\sigma}\right); 1\right). \end{aligned}$$

- The distribution function of USN:

$$\begin{aligned} F_{\text{USN}}(x; \mu, \sigma, \alpha) &= \Phi_1\left(\frac{x - \mu}{\sigma}; 1\right) - 2T\left(\frac{x - \mu}{\sigma}; \alpha\right), \\ T(x; \alpha) &:= \frac{1}{2\pi} \int_0^\alpha \frac{e^{-\frac{1}{2}x^2(1+y^2)}}{1+y^2} dy \quad : \text{Owen's T-function.} \end{aligned}$$

Density Plots (by Wikipedia)



Conditional Probability

- Filtered conditional probabilities are *conditionally skew-normal*:

$$\pi_t(dz) = f_{\text{GMSN}} \left(z; a, \tilde{b}(t, Z_0, Z_t), A, \tilde{B}_t, C \right) dz, \quad t \in [0, T),$$

where

$$\begin{aligned} \tilde{b}(t, Z_0, Z_t) &:= (V_{T-t}^{-1} - V_T^{-1} + B^{-1})^{-1} \{ V_{T-t}^{-1} \mu_{T-t}(Z_t) - V_T^{-1} \mu_T(Z_0) + B^{-1} b \}, \\ \tilde{B}_t &:= (V_{T-t}^{-1} - V_T^{-1} + B^{-1})^{-1}. \end{aligned}$$

Conditional/Transition Probability

Let

$$G(dx) := \mathbb{P}(X \in dx) = f_{\text{GMSN}}(x; a, \mu_T(Z_0), A, V_T, C) dx.$$

■ Filtered conditional probability:

$$\pi_t(dz) = f_{\text{GMSN}}(z; a, \mu_{T-t}(Z_t), A, V_{T-t}, C) dz, \quad t \in [0, T),$$

■ Transition probability:

$$q(s, x; t, y | Z_0) = q(s, x; t, y) = f_{\text{GMSN}}\left(y; \tilde{a}_t, \mu_{t-s}(x), \tilde{A}_{T-t}, V_{t-s}, \tilde{C}_{T-t}\right),$$

where $\tilde{a}_t := a - C \left(\int_0^t e^{uK} du \right) k$, $\tilde{A}_t := A + CV_t C^\top$, $\tilde{C}_t := C e^{tK}$.

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- Initial value *independent!* (Z, \mathcal{F}_t^Z) and (Y, \mathbb{P}^G) become **(completely) Markov**.
- Totally different approach: Corns and Satchell (2007), inspired by Itô-McKean's skew-BM.

Lemma

For

$$f_{\text{GMSN}}(x; a, b, A, B, C) := \frac{1}{\Phi_m(Cb - a, A + CBC^\top)} \phi_n(x - b, B) \Phi_m(Cx - a, A),$$

it holds that

$$\begin{aligned} & \exp\left(-\frac{1}{2}y^\top Py + p^\top y\right) f_{\text{GMSN}}(y; a, b, A, B, C) \\ &= f_{\text{GMSN}}\left(y; a, \tilde{b}, A, \tilde{B}, C\right) \\ & \quad \times \frac{1}{\sqrt{\det(I + BP)}} \frac{\Phi_m(C\tilde{b} - a; A + C\tilde{B}C^\top)}{\Phi_m(Cb - a; A + CBC^\top)} \exp\left\{\frac{1}{2}\left(\tilde{b}^\top \tilde{B}^{-1}\tilde{b} - b^\top B^{-1}b\right)\right\}, \end{aligned}$$

where $\tilde{b} := (P + B^{-1})^{-1}(p + B^{-1}b)$ and $\tilde{B} := (P + B^{-1})^{-1}$.

Sketch for Transition Density

$$q(s, x; t, y | z_0) = \frac{p_{t-s}(x, y) \int_{\mathbb{R}^n} J_{t,T}(z; z_0, y) dz}{\int_{\mathbb{R}^n} J_{s,T}(z; z_0, x) dz},$$

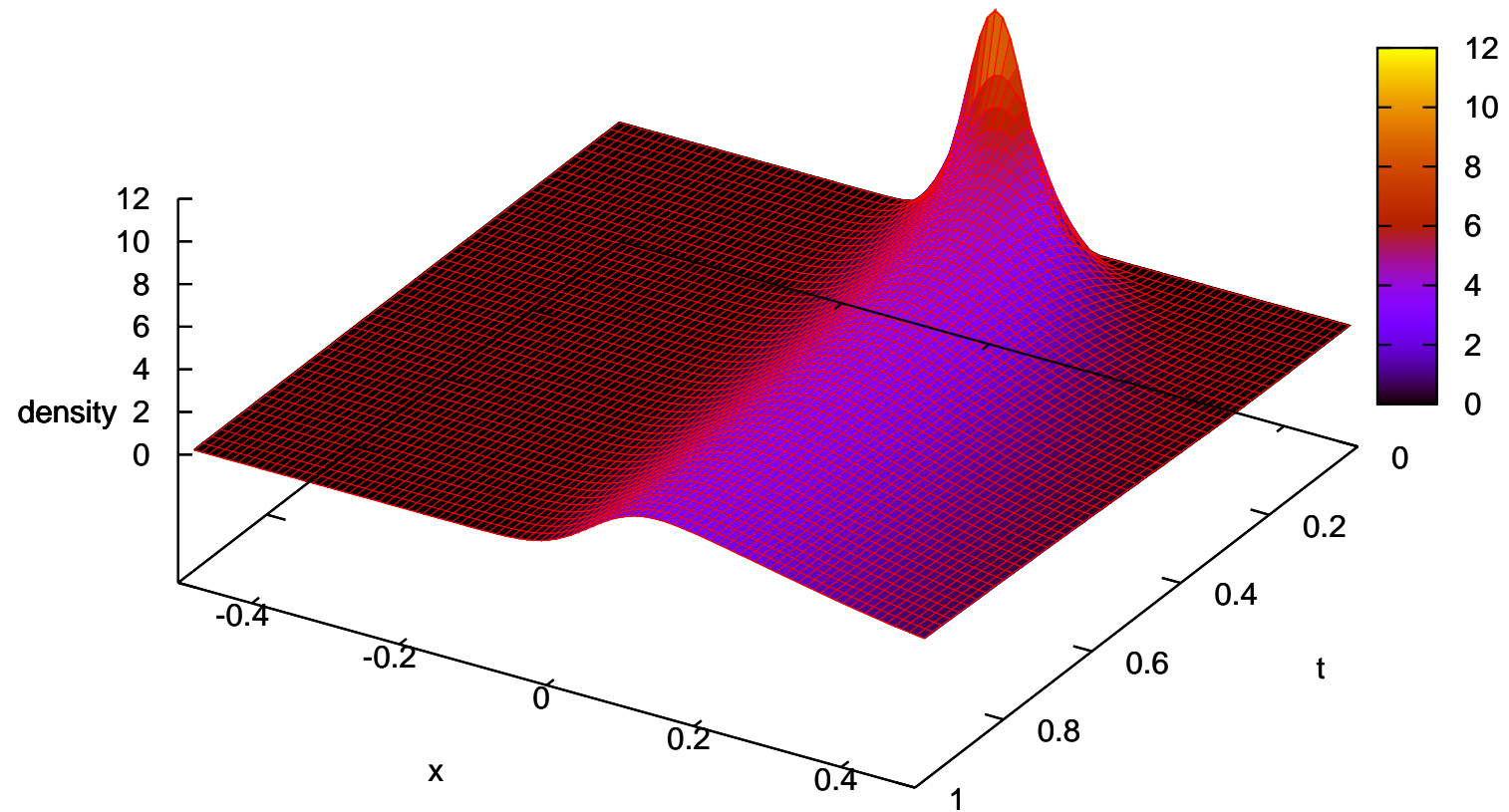
$$J_{t,T}(z; z_0, y) := \frac{p_{T-t}(y, z)}{p_T(y_0, z)} f_{\text{GMSN}}(z; a, \mu_T(z_0), A, V_T, C)$$

$$= C_{t,T} \exp(\text{"quadratic in } z\text{"}) f_{\text{GMSN}}(z; a, \mu_T(z_0), A, V_T, C)$$

$$= \tilde{C}_{t,T} f_{\text{GMSN}}(z; a, \tilde{\mu}_T(z_0), A, \tilde{V}_T, C)$$

Marginals of Skew-Normal Diffusion

Marginal Densities of Skew-Normal Diffusion



Condition Multiple Marginals: $\mathbb{Y} := (Y_{T_1}, \dots, Y_{T_N})$ ($N \geq 2$)

- In “strong” approach, concatenate RMBs.
- In “weak” approach, assuming $G(dy) = g(y)dy$, compute the martingale density process

$$L_t := \frac{d\mathbb{P}_{y_0}^G}{d\mathbb{P}} \Big|_{\mathcal{F}_t} = \mathbb{E} [H(\mathbb{Y}|y_0) \mid \mathcal{F}_t], \quad t \in [0, T],$$

$$H(y_1, \dots, y_N | y_0) := \frac{g(y_1, \dots, y_n)}{\prod_{j=1}^N \tilde{p}_{T_j - T_{j-1}}(y_{j-1}, y_j)}.$$

(Y, \mathbb{P}^G) -dynamics is obtained by Girsanov.

Condition Multiple Marginals: $\mathbb{Y} := (Y_{T_1}, \dots, Y_{T_N})$ ($N \geq 2$)

- In “strong” approach, concatenate RMBs.
- In “weak” approach, assuming $G(dy) = g(y)dy$, compute the martingale density process

$$L_t := \frac{d\mathbb{P}_{y_0}^G}{d\mathbb{P}} \Big|_{\mathcal{F}_t} = \mathbb{E} [H(\mathbb{Y}|y_0) \mid \mathcal{F}_t], \quad t \in [0, T],$$

$$H(y_1, \dots, y_N | y_0) := \frac{g(y_1, \dots, y_n)}{\prod_{j=1}^N \tilde{p}_{T_j - T_{j-1}}(y_{j-1}, y_j)}.$$

(Y, \mathbb{P}^G) -dynamics is obtained by Girsanov.

Notes:

- (Y, \mathbb{P}^G) and (Z, \mathcal{F}_t^Z) are **NON-Markov** in general.
- Calculations of L_t ($t \in [0, T]$) are complicated (including $N \times n$ -dim integrations).

Markov Example

$$H(y_1, \dots, y_N | y_0) = h_0(y_0)h_1(y_1) \cdots h_N(y_N), \text{ i.e.,}$$

$$g(y_1, \dots, y_N | y_0) = h_0(y_0)h_1(y_1) \cdots h_N(y_N) \prod_{j=1}^N \tilde{p}_{T_j - T_{j-1}}(y_{j-1}, y_j).$$

- Markov chain structure: $g(y_1, \dots, y_n | y_0) = \prod_{k=1}^n g_k(y_k | y_{k-1})$, where

$$g_k(y_k | Y_{T_{k-1}}) = g_k(y_k | Y_{T_1}, \dots, Y_{T_{k-1}})$$

is the conditional pdf of Y_{T_k} given $Y_{T_{k-1}}$ (or given $(Y_{T_1}, \dots, Y_{T_{k-1}})$) under \mathbb{P}^G .

- ◆ Can employ arbitrary conditional marginals, selecting h_1, \dots, h_N .

Skew-Normal Example

- Choose arbitrary GMSN (conditional) densities s.t.

$$g_k(y_k|y_{k-1}) := f_{\text{GMSN}}(y_k; a_k, \mu_{T_k-T_{k-1}}(y_{k-1}), A_k, V_{T_k-T_{k-1}}, C_k), \quad k = 1, \dots, N,$$

$$a_k \in \mathbb{R}^m, \quad b_k \in \mathbb{R}^n, \quad A_k \in \mathbb{S}_{++}^m, \quad B_k \in \mathbb{S}_{++}^n, \quad C_k \in \mathbb{R}^{m \times n}, \quad m \in \mathbb{N}, \quad n \in \mathbb{N}. \quad \text{i.e.,}$$

$$h_k(y_k) = \frac{\Phi_m(C_k y_k - a_k, A_k)}{\Phi_m(C_{k+1} \mu_{T_{k+1}-T_k}(y_k) - a_{k+1}, A_{k+1} + C_{k+1} V_{T_{k+1}-T_k} C_{k+1}^\top)},$$

recalling

$$\mu_{T_k-T_{k-1}}(Y_{T_{k-1}}) = \mathbb{E}[Y_{T_k} | Y_{T_{k-1}}], \quad V_{T_k-T_{k-1}} = \mathbb{V}[Y_{T_k} | Y_{T_{k-1}}].$$

- ◆ (Y, \mathbb{P}^G) is a (time-inhomogeneous) skew-normal diffusion.
- ◆ Explicit formulas of transition/conditional probabilities.